

Approximate Heading From A Filtered Heading Sensor During A Turn

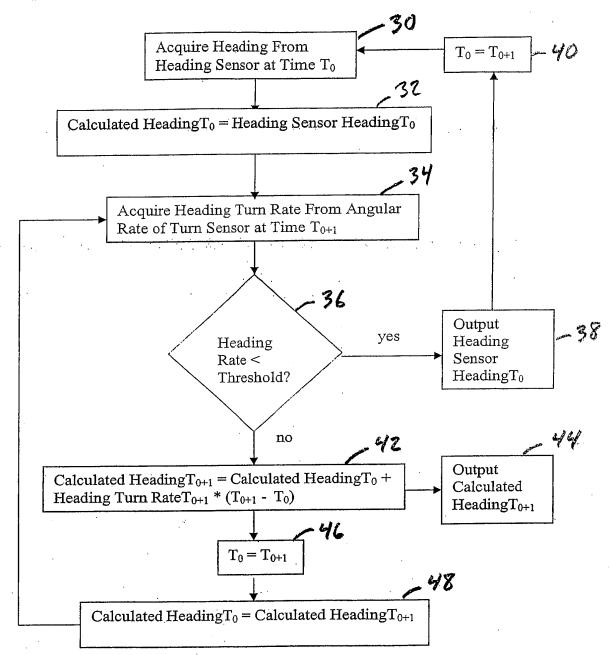


FIG. 2

Approximate Heading Between GPS Updates

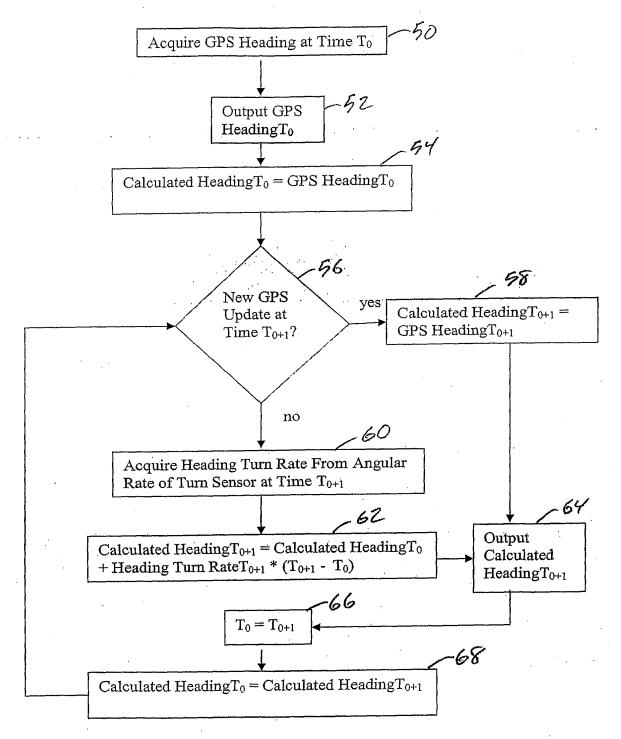


FIG. 3

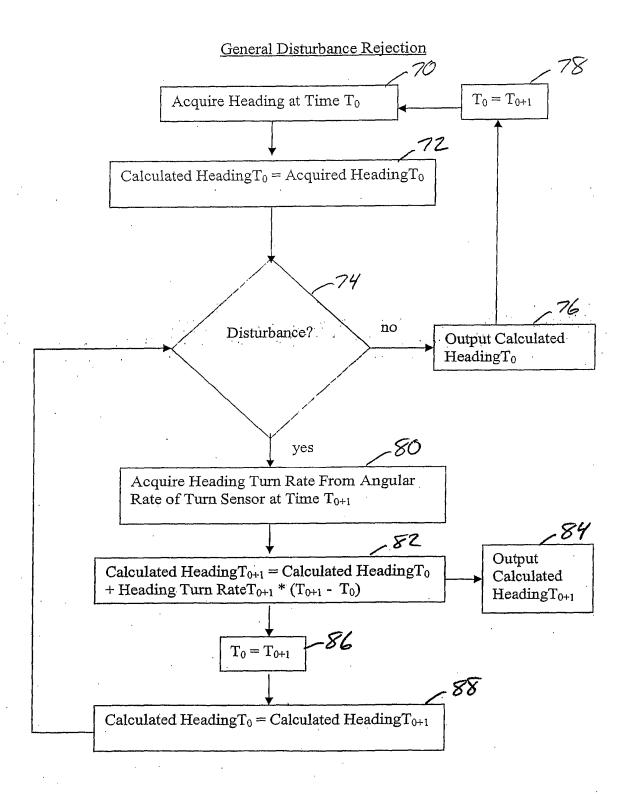


FIG. 4

Disturbance Rejection

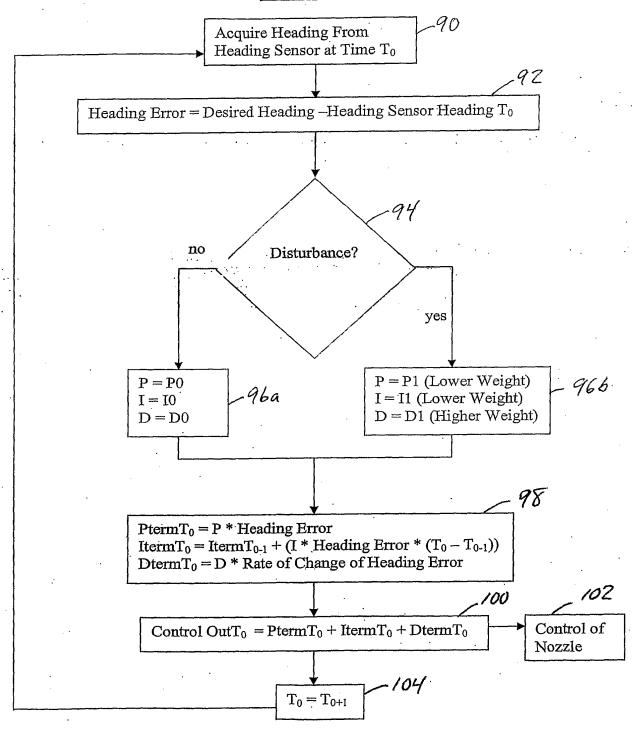


FIG. 5

Disturbance Rejection With Predetermined Data Correction

